

Evaluation of Classification and Regression Algorithms

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Introduction

Evaluation is important

- o to users
	- Model Selection:

It enables to determine which ML system (classifier) should be used

• Trustability:

It enables to determine whether the outputs can be trusted,

- to the designers of ML algorithms
	- It enables to determine whether the outputs can be trusted,
	- It enables to determine which ML system (classifier) should be used, Importance to designers:
	- It enables them to design better systems (incorporate those subsystems that lead to better performance)

Evaluation Criteria

Different measures provide different perspective:

- Error rate (or success rate),
- Learning time (train time),
- Test time (time in using the model)
- Size of the model generated,
- Model interpretability.

The focus here is on Error rate (or success rate)

Loss Functions

- Assume we have an unknown function $f(.)$ that label the examples: $y = f(x)$. A labelled example is a pair of the form (x_i, y_i) ;
- Using a set of labelled examples, we learn an approximation function $\hat{f}(x)$.
- A loss function measures the goodness of that approximation. How to quantify the goodness of fit?

Loss Functions

• Assume an observation x.

The true label (unknown) is $y = f(x)$.

- The learned function assigns the label $\hat{y} = \hat{f}(x)$.
- \bullet Dependent on the domain of y, we use different loss functions to quantify the matching between y and \hat{y} .

- For classification problems, $y \in \{y_1, \ldots, y_k\}$, for regression problems $v \in \Re$.
	- Classification: 0-1 loss function:
		- $\log s(y, \hat{y}) = 1$ iif $y \neq \hat{y}$; 0 iif $y = \hat{y}$
	- Regression:
		- Squared error: $loss(y, \hat{y}) = (y \hat{y})^2$
		- Absolute error: $loss(v, \hat{v}) = |v \hat{v}|$

Sample versus True Error

It is useful to distinguish between:

- **•** True error
- Measured error on a data sample (provides basis for estimating the true error)

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Sample Error

It is useful to distinguish between:

- **•** Resubstitution error (error measured on the train data / biased estimator),
- **•** Generalization error (error measured on the test data / unbiased estimator).

Golden Rule:

Error estimates should be measured on test data independent from the training data.

Score Functions for Predictive Models

Zero-One Loss (Misclassification error):

$$
\frac{\sum_{i=1}^{N} I(y_i \neq \hat{y}_i)}{N}
$$

where

- \bullet $I(exp)$ is the identity function which is 1, if exp is true and 0 otherwise
- \bullet y_i represents the observed value of the class variable of i-th example,
- \hat{y}_i represents the predicted value of the class variable of i-th example,

• N represents the number of examples.

Different Objectives of Evaluation

- We have 1 algorithm (classifier) and 1 dataset: We want to know the estimate of the generalization error
- We have 2 algorithms (classifiers) and 1 dataset: We want to determine whether
	- one is better than another (in terms of the generalization error),
	- both have a comparable generalization error.
- We have N algorithms (classifiers) and M datasets: We want to order (rank) the algorithms taking into account the generalizations errors on all datasets

Methods for Estimating the Error

Methods oriented for 1 algorithm on 1 dataset:

- Train and test (holdout) (is useful if we have many cases)
- Cross-validation (CV) (is useful is we have fewer cases)
- **o** Leave-one-out CV
- Bootstrap

In each case, we consider the estimation of:

- The most likely value (mean)
- **o** Interval of confidence

Method Train and Test (Holdout)

Train and test method:

- Select a part of data for training (e.g. 70%), (stratified selection is better (see below))
- Select the remainder for testing (e.g. remaining 30%),
- **•** Train the algorithm (classifier) on the train data,
- Use the algorithm (classifier) to classify cases using the test data,
- **Calculate the error rate.**

Stratified selection for samples: Maintain similar proportions of the cases of each class as in the full dataset

Cross Validation (CV)

Divide the data into N (e.g. $N = 10$) partitions (stratified selection is better)

- For $i = 1$ to N
	- \bullet Use all partitions except *i* for training,
	- Keep i_{th} partition for testing,
	- Train the algorithm to learn a classifier from the training data,
	- Use the classifier to classify cases using the test data,
	- **Calculate the error rate.**
- Repeat
- Stratified selection for samples: Maintain similar proportions of the cases of each class as in the full dataset
- An interesting property: each example will appear once in the test set

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Cross Validation (10-CV)

Leave-One-Out and Bootstrap

Leave-One-Out

- A special case of cross-validation.
- Used when we have a small number N of cases (e.g. $N=30$),
- \bullet the data is divided into N partitions, and so the test partition contains always just one case.

Bootstrap

- Useful if we have a small number of cases.
- The train set is augmented by including some cases more than once (sampling with replacement).
- The test set contains all cases not used for training. (Both sets should be disjoint, however)

Example: Evaluating Classifiers in R

Example using dataset iris:

```
> data(iris)
> str(iris)
'data.frame': 150 obs. of 5 variables:
$ Sepal.Length: num 5.1 4.9 4.7 4.6 5 5.4 4.6 5 4.4 4.9 ...
$ Sepal.Width : num 3.5 3 3.2 3.1 3.6 3.9 3.4 3.4 2.9 3.1 ...
$ Petal.Length: num 1.4 1.4 1.3 1.5 1.4 1.7 1.4 1.5 1.4 1.5 ...
$ Petal.Width : num 0.2 0.2 0.2 0.2 0.2 0.4 0.3 0.2 0.2 0.1 ...
$ Species : Factor w/ 3 levels "setosa", "versicolor",..: 1 1 1 1 1
```


Evaluating Classifiers in R

Generate train and test set without permutation:

- > last <-0.7*nrow(iris)
- > train <-iris[1:last,]
- $>$ test \le -iris $[-(1:last),]$

Generate train and test set, while permuting data:

- > permute.index <-sample(1:nrow(iris), 0.7*nrow(iris))
- > train <-iris[permute.index,]
- > test <-iris[-permute.index,]

Generating predictions

Train the algorithm (classifier) on the train data,

```
> library(rpart)
> arv <-rpart(Species ~ . , train)
> arv
n= 105
node), split, n, loss, yval, (yprob)
* denotes terminal node
1) root 105 69 setosa (0.3428571 0.3142857 0.3428571)
2) Petal.Length< 2.45 36 0 setosa (1.0000000 0.0000000 0.0000000) *
3) Petal.Length>=2.45 69 33 virginica (0.0000000 0.4782609 0.5217391)
6) Petal.Length< 4.75 29 0 versicolor (0.0000000 1.0000000 0.0000000) *
7) Petal.Length>=4.75 40 4 virginica (0.0000000 0.1000000 0.9000000) *
```


Ploting the Decision Tree

- > plot(árvore)
- $>$ text($árvore$)

Improved tree plot:

- > show.tree <-function(arvore) {
- + plot(arvore,uniform=T,branch=0)
- + text(arvore,digits=3,cex=0.65,
- + font=10, pretty=0,fancy=T,fwidth=0,
- + fheight=0)

+}

> show.tree(arvore)

Other improvements: > help(plot.rpart)

Generating predictions

Predict the classifier on the test data,

```
> preds <- predict(arv, test, type="class")
> table(preds)
preds
setosa versicolor virginica
14 16 15
```
Generate confusion matrix:

```
> mc <- table(preds,test[,5])
> mc
preds setosa versicolor virginica
setosa 14 0 0
versicolor 0 15 1
virginica 0 2 13
```


 $\mathbf{A} \equiv \mathbf{A} + \mathbf{A} + \mathbf{B} + \mathbf{A} + \math$

Calculating Error

- Number of examples classified $>$ sum(mc)
- Calculate the total of correct classifications on the diagonal of the confusion matrix:
	- $>$ diag(mc)
	- $>$ sum(diag(mc))
- Calculate the accuracy rate: $>$ sum(diag(mc))/sum(mc)
- Calculate the error rate: $> 1 - \text{sum}(diag(mc)) / \text{sum}(mc)$

Implementing 10-fold CV

```
#Randomly shuffle the data
data<-iris[sample(nrow(iris)),]
```

```
#Create 10 equally size folds
folds <- cut(1:nrow(data),breaks=10,labels=FALSE)
```

```
#Perform 10 fold cross validation
for(i in 1:10){
testData \leftarrow data[folds == i, ]
trainData <- data[folds != i, ]
```
 $%$ #Use the test and train data partitions however you desi: . . . }

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Cross-validation in KNIME

Cross-validation in KNIME

Estimating Intervals of Confidence

- Consider some hypothesis $h(x)$.
- \bullet Given a sample S of size n, we can calculate the $e = error(h|S)$.
- What can be infered about the error in the population $p = error(h|P)$?
- \bullet We cannot compute p, but can deduce an interval that contains p for a given confidence level.

Given that error rate follows a binomial distribution:

Confidence Interval

$$
CI = e \pm z \times \sqrt{\frac{e \times (1-e)}{n}}
$$

where z can be looked up in a table of the binomial distribution and depends on the confidence level.

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Intervals of Confidence for Train / Test

Computing the sample error, error($h(S)$, using Train and Test. error(h|P) \approx error(h|S), and $var(error(h|P)) = \frac{error(h|S) \times (1-error(h|S))}{n}$ The interval of confidence can be derived analytically:

Interval of Confidence

Given a confidence level α , error(h|P) is contained in the interval

$$
error(h|P) = error(h|S) \pm z_{\alpha} \sqrt{\frac{error(h|S) \times (1 - error(h|S))}{n}}
$$

 $\left\{ \begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0$

If the confidence level is 95%, then $z_{\alpha} = 1.26$

Example

- \bullet e=10/100 (10 errors in 100 (n=100)
- \bullet The given confidence level is 95% This determines $z = 1.96$
- z value that can be looked up in a table for binomial distribution and given confidence level (e.g. 95%)
- The confidence interval is: $CI = e \pm z \times \sqrt{\frac{e \times (1-e)}{n}}$ n

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$$
CI = 0.1 \pm 1.96 \times \sqrt{\frac{0.1 \times (1 - 0.1)}{100}}
$$

 0.1 ± 0.058

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Comparing the Performance of 2 Classifiers

One possible objective mentioned earlier: We have 2 algorithms (classifiers) and 1 dataset:

We want to determine whether

• one algorithm is better than another (in terms of the generalization error),

• both have a comparable generalization error.

We will orient our analysis to CV.

Example

Consider the following example:

• Errors of classifier A: 0.100 0.094 0.109 0.091 0.096 0.104 0.102 0.089 0.091 0.106

\bullet Errors of classifier B: 0.104 0.113 0.107 0.106 0.123 0.108 0.104 0.119 0.095 0.114

Is A better than B? Or vice versa? Or are they comparable?

Example

Comparing two Algorithms

Dotted line represents equal performance of both algorithms.

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Hypothesis Test

- We cannot simply compare the means, as the difference might be only by chance and are not statistically significant.
- The proper way is to conduct a hypothesis test that should answer the question whether the two samples belong to two identical populations (null hypothesis) or to two different populations (alternative hypothesis).
- Let μ_A and μ_B represent the mean errors of two models in CV evaluation. We can formulate:
	- Null hypothesis: $H0 = \mu_A \mu_B = 0$
	- Alternative hypothesis: $H1 = \mu_A \mu_B \neq 0$
- The objective of a statistical test is to accept / reject the null hypothesis (and hence accept the alternative hypothesis) Different statistical tests that can be used.

Statistical Tests

- Parametric tests make assumptions about the underlying distribution (e.g. that it is normal) Example: (t-test)
- Non-Parametric tests do not make any assumptions about the underlying distribution. Example: Wilcoxon signed-rank test, McNemar test

With CV, always use the variant of **matched pairs**:

- Match errors on corresponding folds of CV.
- Both algorithms are trained and evaluated in the same conditions (same train and test set)
- This test has greater statistical power.

Use two-sided tests.

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Tests based on Student Distribution

To determine whether two means are statistically different, calculate:

- the differences of errors $d_i = e_{a_i} e_{b_i}$
- **o** the mean of all differences d
- Student distribution $t=d/(\sqrt{\sigma^2/k})$
- Use table for t-distribution with $k 1$ degrees of freedom (n^o of observations) to establish the limit z for a given confidence level

If confidence level is 95%, z is 1.83.

• Determine whether t exceeds the limit z (either $t > z$ or $t < -z$) If it does, the means are significantly different.

Conducting t-test in R: Example

```
> a
[1] 0.100 0.094 0.109 0.091 0.096 0.104 0.102 0.089 0.091 0.106
> b
[1] 0.104 0.113 0.107 0.106 0.123 0.108 0.104 0.119 0.095 0.114
> t.test(a,b,alternative="two.sided", conf.level = 0.95)
Welch Two Sample t-test
data: a and b
t = -3.2721, df = 17.598, p-value = 0.004333
alternative hypothesis: true difference in means is not equal to 0
95 percent confidence interval:
-0.018238664 -0.003961336
sample estimates:
mean of x mean of y
0.0982 0.1093
```


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Wilcoxon signed-rank tests (non-param.)

Wilcoxon signed rank test:

- Calculate differences of performance measure of models A,B
- Calculate the absolute value of the differences
- Rank the absolute values values
- Can we distinguish the values of A from those of B?

Wilcoxon signed-rank tests

• Calculate the mean value $R+$ of ranks in which B is better than A

(average ranks of ties)

- Repeat for R− where B is worse than A. (average ranks of ties)
- Determine S, the minimum of $R+$ and $R-$.
- Look up a critical value z in a table for given S, N. or alternatively if $N > 25$, use a formula: $z = \frac{S-1/4N(N-1)}{\sqrt{1/24N(N+1)/2N}}$ $1/24N(N+1)(2N+1)$

• Assuming confidence level of 95% (a=0.05) reject null hypothesis, if $z < -1.96$.

(see Gama et al.: E.C.D., p.204 for more details)

Wilcoxon signed-rank tests in R

```
> a \leq c(0.100.0.094.0.109.0.091.0.096.0.104.0.102.0.089.0.091.0.106)> b \lt\lt (0.104, 0.113, 0.107, 0.106, 0.123, 0.108, 0.104, 0.119, 0.095, 0.114)> ?wilcox.test
> wilcox.test(a,b)
        Wilcoxon rank sum test with continuity correction
data: a and bW = 14.5, p-value = 0.008008
alternative hypothesis: true location shift is not equal to 0
```


Problem with repeated tests

- If we repeat tests, there is some chance that the test will return a wrong result.
- There are two possibilities (Type I and Type II errors):
	- The method should reject a null hypothesis, but it did not.
	- The method should not reject a null hypothesis, but it did.

- These errors arise due to the statistical nature of the test.
- \bullet If the given confidence is, say, 95%, we can expect that in approximately 5% of cases the test will go wrong.
- So, if we repeat test, we need to carry out a Bonferroni adjustment.

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Adjustment for Multiple Tests

Bonferroni adjustment is used to adjust the confidence level:

$$
\alpha_n=1-(1-a)^n
$$

where n is the number of repetitions.

Ex. If the test is repeated twice, we need to adjust 95% to: $\alpha = 1 - (1 - 0.95)^2 = 0.9975$

Problems with t-tests

Although t-tests are commonly used, the test is being criticized as not somewhat problematic:

- The training data used in different folds of CV is not independent,
- The test assumes normal distribution

Some authors suggest

Using 10*10-fold CV, with permutation of the data in each run,

Wilcoxon matched-pairs signed-rank test.

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Comparing N Classifiers

Suppose our task it use N classifiers on M different datasets and determine which one(s) provide the best performance. There are different types of answers we may seek to respond:

- Identify the best classifier,
- Identify the best classifier and all equivalent ones within critical distance,
- Provide a ranking of classifiers,
- Provide a ranking of groups of classifiers.

How should we proceed?

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Approach based on Ranks of Performance

The approach currently used is based on ranks of performance (following Demsar, 2006)

- **Q.** Construct a table where :
	- columns represent classifiers,
	- rows represent datasets,
	- value $\langle i, j \rangle$ represents a rank of performance of classifier *j* on dataset i
- \bullet obtained as a result of evaluation (e.g. running CV)
- Elaborate the global measure for each algorithm (column): mean rank
- Elaborate a ranking of the mean ranks.
- This permits to decide which classifier is best overall.

Approach based on Ranks

- The first question that arises is: Are the results of the classification algorithms significantly different?
- This can be determined by Friedman test (non-parametric). The null hypothesis is that there is no difference among the classifiers. If the null hypothesis is rejected, we can proceed with a post-hoc tests.
- **•** The process involves calculation a Friedman statistic F_F , which is a function of :

N the number of datasets,

A is the number of algorithms

 R_J mean ranks of algorithms.

$$
F_F = \frac{(N-1)\chi_F^2}{N(A-1)-\chi_F^2} \quad \chi_F^2 = \frac{12N}{A(A+1)}[\sum_j R_j^2 - \frac{A(A+1)^2}{4}]
$$

B

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Approach based on Ranks

- The null hypothesis is rejected if the statistic F_F is greater than $F_{A-1,(A-1)(N-1)}$ where $A - 1$ and $(A - 1)(N - 1)$ represent the degrees of freedom.
- The value of $F_{A-1,(A-1)(N-1)}$ can be retrieved from books on statistics.
- If the null hypothesis is rejected, we can proceed with post-hoc test.

Approach based on Ranks

Post-hoc tests can determine whether the performance of two classifiers is significantly different.

In post-hoc tests we can use:

- Nemenyi test for all pairs of classifiers,
- Bonferoni-Dunn test, where all classifiers are compared to a control classifier.
- We can calculate critical distance CD (function of A, N and q_a) which can be used to determine whether two algorithms are significantly different. This happens if the differences of mean ranks exceed CD:

$$
CD = q_{\alpha}\sqrt{A(A+1)/(6N)}
$$

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Approach based on Ranks

- Comparisons using a Nemenyi test is shown in fig. (a). The best ranked algorithm (A) is shown. Groups of classifiers that are not significantly different are connected.
- Comparisons using a Bonferoni-Dunn test is shown in (b). It assumes that classifiers A,B,C are compared to D.

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Example in R

CD $\overline{2}$ 3 $\overline{\mathbf{5}}$ $>$ library('scmamp') $>$ data(data_gh_2008) $> plotCD(data, gh.2008, alpha = 0.01)$ $C4.5$ CN₂ **NaiveBayes** $k-NN(k=1)$

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"No Free Lunch" Theorems

 $Acc_G(L)$ = Generalization accuracy of learner L $=$ Accuracy of L on non-training examples $\mathcal{F} =$ Set of all possible concepts, $y = f(\mathbf{x})$

Theorem: For any learner L, $\frac{1}{|\mathcal{F}|}\sum_{\mathcal{F}}Acc_G(L) = \frac{1}{2}$ (given any distribution D over x and training set size n)

Proof sketch: Given any training set S: For every concept f where $Acc_G(L) = \frac{1}{2} + \delta$, there is a concept f' where $Acc_G(L) = \frac{1}{2} - \delta$. $\forall \mathbf{x} \in S, f'(\mathbf{x}) = f(\mathbf{x}) = y. \quad \forall \mathbf{x} \notin S, f'(\mathbf{x}) = \neg f(\mathbf{x}).$

Corollary: For any two learners L_1 , L_2 : If \exists learning problem s.t. $Acc_G(L_1) > Acc_G(L_2)$ **Then** \exists learning problem s.t. $Acc_G(L_2) > Acc_G(L_1)$

What Does This Mean in Practice?

- Don't expect your favorite learner to always be best
- Try different approaches and compare
- But how could (say) a multilayer perceptron be less accurate than a single-layer one?

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Bias and Variance

- Bias-variance decomposition is key tool for understanding learning algorithms
- Helps explain why simple learners can outperform powerful ones
- Helps explain why model ensembles outperform single models

- Helps understand $\&$ avoid overfitting
- Standard decomposition for squared loss
- Can be generalized to zero-one loss

Definitions

- Given training set: $\{(\mathbf{x}_1, t_1), \ldots, (\mathbf{x}_n, t_n)\}\$
- Learner induces model: $y = f(\mathbf{x})$
- Loss measures quality of learner's predictions
	- Squared loss: $L(t, y) = (t y)^2$
	- Absolute loss: $L(t, y) = |t y|$
	- Zero-one loss: $L(t, y) = 0$ if $y = t$, 1 otherwise

 $-$ Etc.

• Loss = Bias + Variance + Noise (This lecture: ignore noise; see paper)

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Decomposition for squared loss

$$
(t-y)^2 = (t-\overline{y}+\overline{y}-y)^2
$$

= $(t-\overline{y})^2 + (\overline{y}-y)^2 + 2(t-\overline{y})(\overline{y}-y)$

 $E[(t-y)^2] = (t-\overline{y})^2 + E[(\overline{y}-y)^2]$ Exp. loss = Bias + Variance

(Expectations are over training sets)

How to generalize this to other loss funcs?

$$
E[(t-y)^{2}] = (t - \overline{y})^{2} + E[(\overline{y} - y)^{2}]
$$

$$
(a - b)^2 \rightarrow L(a, b)
$$

\n
$$
E[(t - y)^2] \rightarrow E[L(t, y)]
$$
 (Exp. loss)
\n
$$
(t - \overline{y})^2 \rightarrow L(t, \overline{y})
$$
 (Bias)
\n
$$
E[(\overline{y} - y)^2] \rightarrow E[L(\overline{y}, y)]
$$
 (Variance)

But what should \overline{y} be?

Define Main Prediction:

Prediction with min average loss relative to all predictions

$$
\overline{y}_L = \operatornamewithlimits{argmin}_{y'} E[L(y,y')]
$$

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- Squared loss: \overline{y} = Mean
- Absolute loss: \overline{y} = Median
- Zero-one loss: \overline{y} = Mode

Generalized definitions

Bias = Loss incurred by main prediction = $L(t, \overline{y})$

Variance = Average loss incurred by prediction relative to main prediction = $E[L(\overline{y}, y)]$

These definitions have all the required properties.

For zero-one loss:

Bias =
$$
\begin{cases} 0 \text{ if main prediction is correct} \\ 1 \text{ otherwise} \end{cases}
$$

Variance = Prob(Prediction \neq Main pred) = $P(y \neq \overline{y})$

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Bias-Variance Tradeoff

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Bias-Variance Intuition

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Bias-Variance Tradeoff

Typical behaviour:

- High bias, Low variance Linear Discriminants, Naive Bayes
- **•** Low bias, High variance Decision Trees, Neural Networks

If we increase the number of degrees of freedom of the model:

- **o** Bias will diminish
- Variance will increase
- To minimize the expected error, we need establish a compromise between the two components.

Outline

- **1 [Estimating Performance](#page-2-0)**
- 2 [Comparing 2 Classifiers](#page-28-0)
- **3 [Comparing N Classifiers](#page-42-0)**
- **[Bias Variance tradeoff](#page-50-0)**

Further Reading

- J.Gama, A.de Carvalho, K.Facelli, A. C. Lorena, M.Oliveira: Extração de Conhecimento de Dados, Cap. 9, Ed. Sílabo, 2017.
- T. Mitchell: Machine Learning, McGrawHill, 1997 Chapter 5 Evaluationg Hypotheses
- D.Hand, H. Manilla, P. Smyth: Principles of Data Mining, MIT Press, 2001 Section 7.3 Predictive versus Descriptive Score Functions; Section 10.2 Evaluating and Comparing Classifiers
- M.Berthold,D.Hand: Intelligent Data Analysis, Section 2.5 Prediction and Prediction Error; Section 2.6 Resampling
- J Demsar: Statistical Comparisons of Classifiers over Multiple Data Sets, The Journal of Machine Learning Research, Vol. 7 , 2006, Pages: 1–30.