

Adaptive Filters Prediction and System

Identification

Adaptive Filters

- Adaptation the ability of a system to cope with unexpected disturbances of the environment
- Adaptive System a system whose characteristics are alterable or adjustable in such a way that its behavior or performance improves according to some measure



- Self-adjusting in the face of non-stationary environments and changing system requirements
- Trained, rather than synthesized, to perform particular filtering operations
- Non-linear systems with time-varying parameters



- Inherently difficult to analyze
- Have the potential to outperform non-adaptive systems



- In general, the design of non-adaptive filters requires *a priori* knowledge of the characteristics of the signals involved.
- Given this knowledge, optimal filters may be designed.
- However, as signal characteristics change, these filters may be rendered sub-optimal.



- If knowledge of signal characteristics is inaccurate, incomplete, or unavailable, optimal filter design may not be possible.
- In such cases, adaptive filters that continually seek optimum performance may be of use.



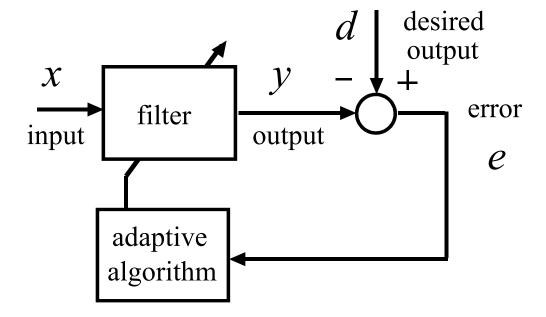
- In general, adaptive systems must be considered non-linear.
- We will consider so-called *linear adaptive filters* if adaptation is disabled, they become linear filters.
- These are useful. They are mathematically tractable and relatively easy to design.



- Adaptive filtering is at the core of much digital signal processing.
- Adaptive filters do not rely on prior knowledge of signal statistics or characteristics to the same extent as non-adaptive filters.

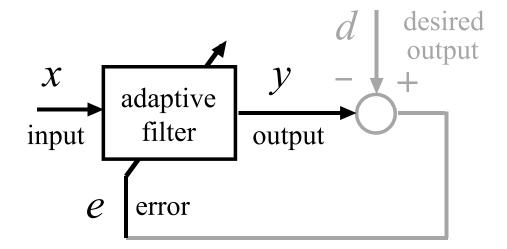


Define the following signals.



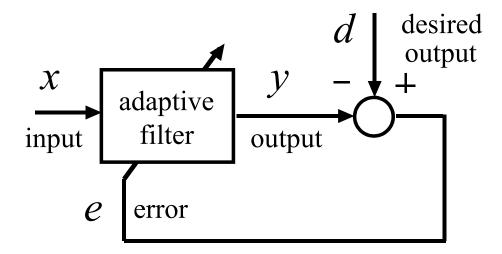


• Alternatively, represent adaptive filter as a single block.



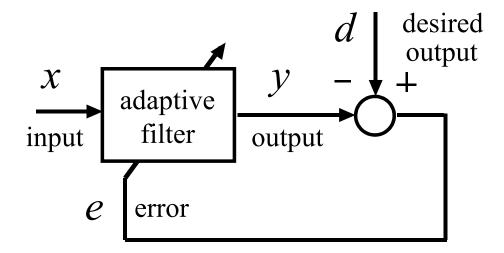


Different closed loop configurations are concerned primarily with how desired output d
is derived.



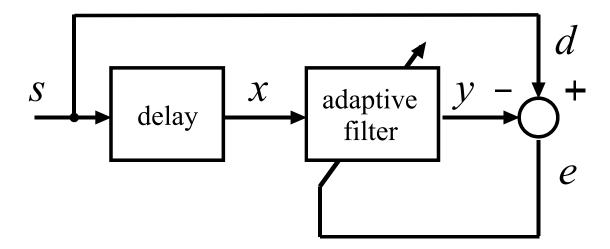


• In each case, however, the adaptive algorithm attempts to minimize error e in some sense.



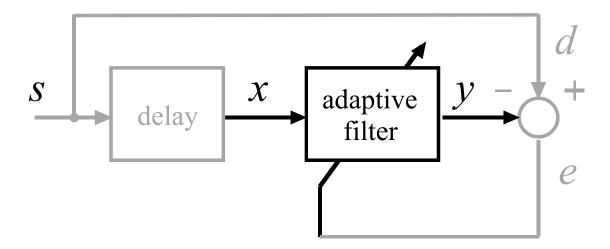


• A *delayed* version of the desired signal *s* is fed to the adaptive filter, which tries to predict the *current* value of the desired signal.



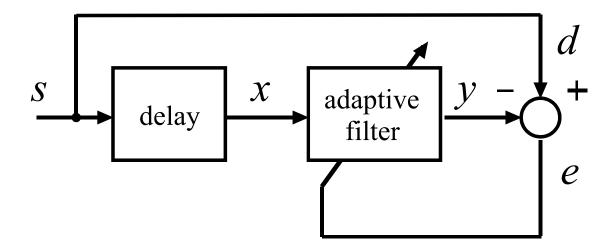


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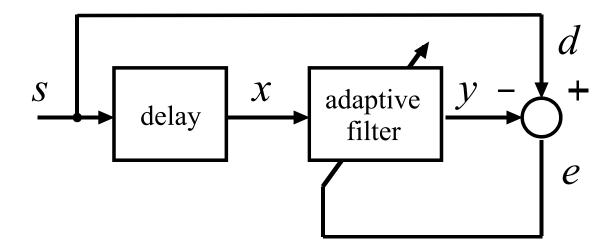


• Prediction is used in signal encoding and noise reduction.



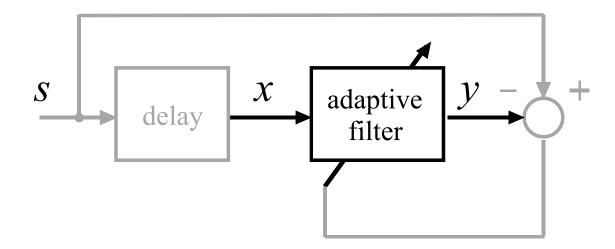


• Filter learns about the process by which the signal *s* is produced.



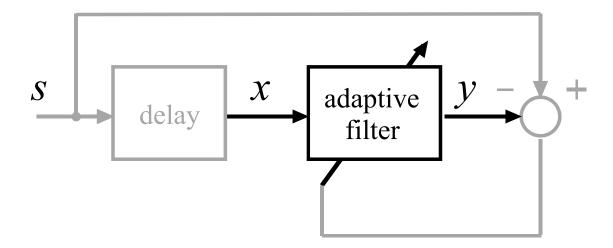


• Once filter has been trained, disable adaptation and remove d.



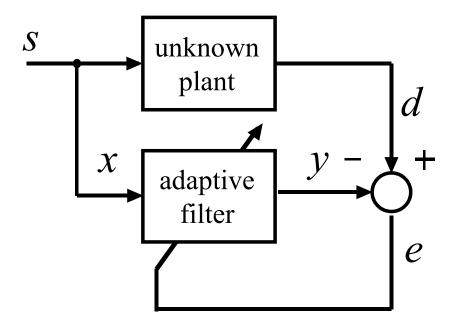


• Filter now predicts future values of *x* from past values.



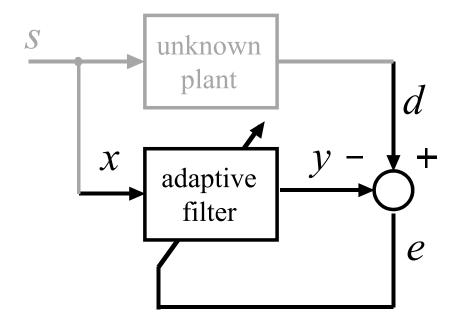


Broadband signal S applied to inputs of both unknown system and adaptive filter



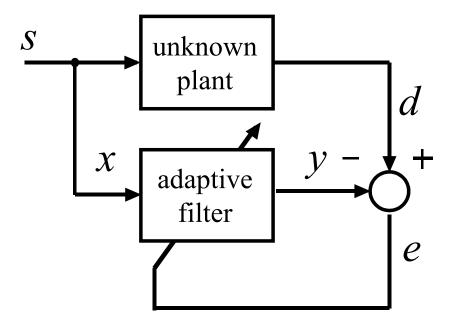


Broadband signal S applied to inputs of both unknown system and adaptive filter



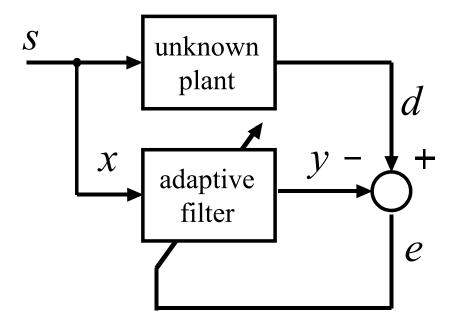


• Adaptive filter tries to emulate characteristics of unknown plant.



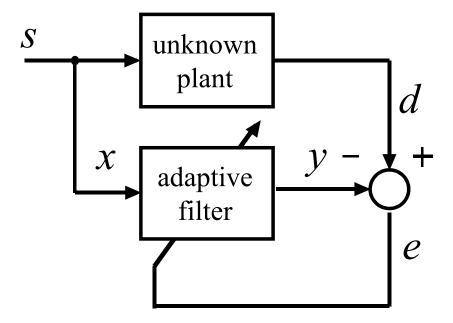


After (successful) adaptation, plant characteristics have been identified.



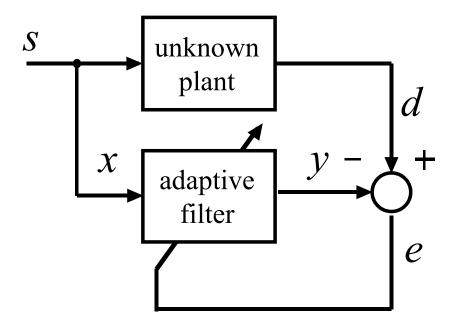


Adaptive filter has learned input-output characteristics of unknown plant.



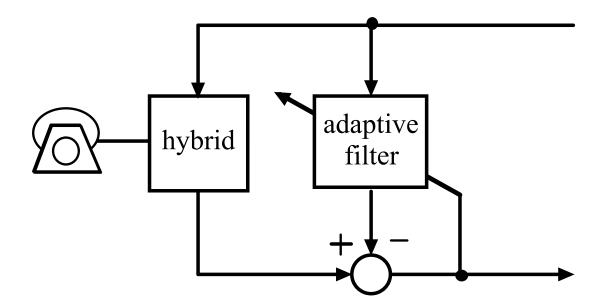


Similar inputs to adaptive filter and unknown plant will yield similar outputs.



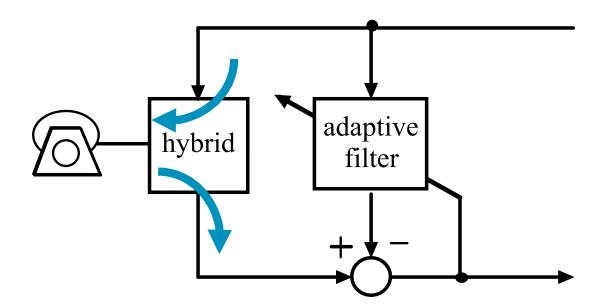


Long-distance telephone echo cancellation



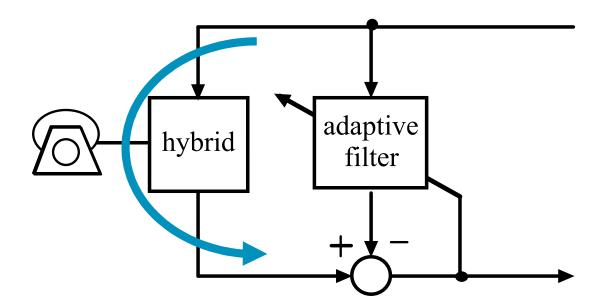


• Ideally, hybrid routes incoming signal to and outgoing signal from telephone.



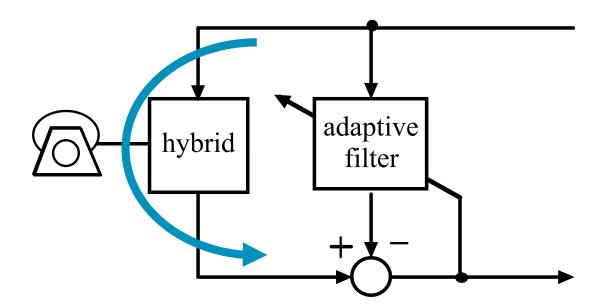


• Due to impedance mismatches, some of the incoming signal is returned.



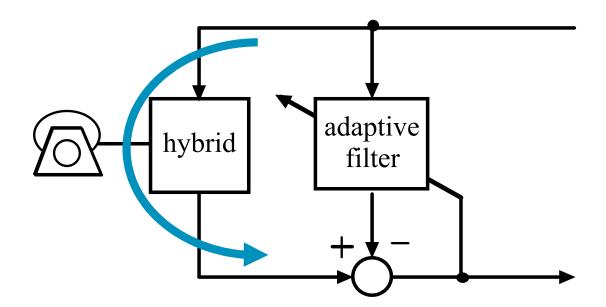


• Resultant *echo* can be distracting if connection is long-distance.





• This *hybrid leakage path* is modeled by the adaptive filter.





Adaptation should be disabled in the presence of an outgoing signal.

